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Neumann Traces

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RECOVERING THE INITIAL DATA OF THE WAVE EQUATION FROM NEUMANN TRACES*

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Abstract

We study the problem of recovering the initial data $(f, 0)$ of the standard wave equation from the Neumann trace (the normal derivative) of the solution on the boundary of convex domains in arbitrary spatial dimension. Among others, this problem is relevant for tomographic image reconstruction including photoacoustic tomography. We establish explicit inversion formulas of the back-projection type that recover the initial data up to an additive term defined by a smoothing integral operator. In the case that the boundary of the domain is an ellipsoid, the integral operator vanishes, and hence we obtain an analytic formula for recovering the initial data from Neumann traces of the wave equation on ellipsoids.

Keywords. Image reconstruction, wave equation, inversion formula, Neumann trace, computed tomography.

AMS subject classifications: 35R30, 44A12, 35L05, 92C55.

1 Introduction

The problem of determining the initial data of the wave equation from indirect observations arises in various practical applications. Well-known examples include photoacoustic tomography, ultrasound tomography, SONAR or seismic imaging (see, for example, [36, 34, 19, 32, 30, 25, 23, 31, 6]). These applications are often well modeled by the standard wave equation

$$\begin{aligned} (\partial_t^2 - \Delta)u(x, t) &= 0 && \text{for } (x, t) \in \mathbb{R}^n \times (0, \infty), \\ u(x, 0) &= f(x) && \text{for } x \in \mathbb{R}^n, \\ (\partial_t u)(x, 0) &= g(x) && \text{for } x \in \mathbb{R}^n, \end{aligned} \tag{1.1}$$

where (f, g) with $f, g: \mathbb{R}^n \rightarrow \mathbb{R}$ are the initial data, Δ denotes the Laplacian in the spatial component $x \in \mathbb{R}^n$, ∂_t the partial derivative with respect to the time $t > 0$ and $n \in \mathbb{N}$ with $n \geq 2$ denotes the spatial dimension.

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For example, in photoacoustic tomography (PAT), g is the zero function and $f \in C_c^\infty(\Omega)$ a smooth function with compact support in a bounded domain $\Omega \subset \mathbb{R}^n$ modeling the initial pressure distribution. The corresponding inverse problem of PAT is to determine the initial data $(f, 0)$ in (1.1) from data measured on the boundary of Ω . Throughout this paper we will consider the inverse problem of PAT, where we assume given data in the form of Neumann traces described below.

1.1 Inversion from Dirichlet and Neumann traces

Most image reconstruction methods in PAT assume that the measured data consists of the Dirichlet trace $u|_{\partial\Omega \times (0, \infty)}$ on $\partial\Omega$. However, as pointed out in [11, 35, 8], PAT measurements are often more accurately modeled by a linear combination of the Dirichlet trace and the normal derivative

$$u_{a,b}(x, t) = au(x, t) + b\partial_\nu u(x, t) \quad \text{for } (x, t) \in \partial\Omega \times (0, \infty), \quad (1.2)$$

which we refer to as the mixed trace on $\partial\Omega$; here $a, b \geq 0$ are constants. See also [2, 1, 7, 29] for modeling and analysis of detectors characteristics in PAT. Measurements of the form (1.2) with $a = 0$ corresponds to the Neumann trace and with $b = 0$ to the Dirichlet trace on $\partial\Omega$. Beside the type of data measured in PAT, we observe from (1.2) that the inversion of the wave equation depends on the domain Ω as well.

In the last twenty years, plenty of results for the inversion of wave equation from Dirichlet measurements have been derived. In particular, exact inversion formulas for Dirichlet data on spheres [13, 12, 20, 26, 37], ellipses [24, 15, 16, 33, 28, 5], quadric hypersurfaces [17, 18, 27] and certain polygons and polyhedra [21, 22] have been developed. However, few theoretical results for Neumann as well as for mixed traces are known. To the best of our knowledge, the only results for this inverse problem are presented in [38], where a series inversion formula for spheres in arbitrary dimension has been established, and [8], where an exact reconstruction formula of a so-called back-projection type has been provided in the case of two spatial variables.

In this paper we study the inverse problem in PAT of recovering the initial data $(f, 0)$ from the Neumann trace on Ω which extend the results of [8] to arbitrary spatial dimension. We separately treat the case of even and odd dimensions which are notable different from each other. Note that the presented results are closely related to the results of [16], where corresponding formulas have been derived for data given for Dirichlet traces. However, while several derivations in [16] are based on formal calculus based on distributions, all results in the present paper are derived rigorously using classical calculus.

1.2 Outline

In the present paper we study the problem of recovering the initial data $f \in C_c^\infty(\Omega)$ in (1.1) with $g = 0$ from Neumann measurements in arbitrary dimension. We provide inversion formulas for convex domains $\Omega \subset \mathbb{R}^n$ with smooth boundary that is exact up to a smoothing integral operator. Moreover we derive an exact inversion formula for

Neumann traces on ellipsoids. The starting point of our results is an integral identity presented in subsection 2.4. Based on this identity, we derive our explicit inversion formulas for even dimensions in section 3 and for odd dimensions in section 4. The paper ends with some conclusions in section 5.

2 Notation and preliminary results

Throughout this paper, whenever $f, g \in C_c^\infty(\Omega)$ are given functions, we write u and v for the solutions of the wave equation (1.1) with initial data $(f, 0)$ and $(0, g)$, respectively.

2.1 Notation

In the whole article, we suppose that $\Omega \subset \mathbb{R}^n$ is a convex domain with smooth boundary $\partial\Omega$. For a function $f \in C_c^\infty(\Omega)$ we denote by

$$\mathcal{M}f: \mathbb{R}^n \times (0, \infty) \rightarrow \mathbb{R}: (x, r) \mapsto \frac{1}{\sigma(\partial\mathbb{B}^n(x, r))} \int_{\partial\mathbb{B}^n(x, r)} f(y) d\sigma(y)$$

the spherical mean operator of f , where $\mathbb{B}^n(x, r)$ denotes the open ball with center $x \in \mathbb{R}^n$ and radius $r > 0$, and σ the standard volume measure on manifolds. For short, we set $\mathbb{S}^{n-1} := \partial\mathbb{B}^n(0, 1)$ as the unit sphere in \mathbb{R}^n .

We also use the notation

$$\mathcal{R}f: \mathbb{S}^{n-1} \times \mathbb{R} \rightarrow \mathbb{R}: (\theta, s) \mapsto \int_{E(\theta, s)} f(y) d\sigma(y)$$

for the Radon transform of f , where the smooth manifold $E(\theta, s) := \{x \in \mathbb{R}^n \mid \langle x, \theta \rangle = s\}$ is defined as the $n-1$ -dimensional hyperplane with normal vector $\theta \in \mathbb{S}^{n-1}$ and oriented distance $s \in \mathbb{R}$.

The Hilbert transform of a function $\varphi: \mathbb{S}^{n-1} \times \mathbb{R} \rightarrow \mathbb{R}$ in the second variable is defined as

$$\mathcal{H}_2\varphi: \mathbb{S}^{n-1} \times \mathbb{R} \rightarrow \mathbb{R}: (\theta, s) \mapsto \frac{1}{\pi} \lim_{\varepsilon \searrow 0} \int_{\mathbb{R} \setminus (s-\varepsilon, s+\varepsilon)} \frac{\varphi(\theta, t)}{s-t} dt,$$

provided the integral for every $\varepsilon > 0$ and the limit exist. If the function $\varphi(\theta, \cdot): \mathbb{R} \rightarrow \mathbb{R}$ is differentiable for some $\theta \in \mathbb{S}^{n-1}$, then we denote its derivative by $\partial_2\varphi(\theta, \cdot)$.

Similarly, we denote by

$$(g *_2 h)(\theta, s) := (g(\theta, \cdot) * h(\theta, \cdot))(s) = \int_{\mathbb{R}} g(\theta, s-x) h(\theta, x) dx$$

the convolution of g with h in the second argument, where $g, h: \mathbb{S}^{n-1} \times \mathbb{R} \rightarrow \mathbb{R}$ and $(\theta, s) \in \mathbb{S}^{n-1} \times \mathbb{R}$.

2.2 Approximation to the identity

In the first auxiliary technical result, we present an approximation to the identity in \mathbb{R}^n , whose Radon transform is again an approximation to the identity in \mathbb{R} for a fixed angle $\theta \in \mathbb{S}^{n-1}$.

Lemma 2.1. *For a positive integer $\mu > 0$ let*

$$\psi_\mu: \mathbb{R}^n \rightarrow \mathbb{R}: x \mapsto \frac{1}{a} \begin{cases} (1 - \|x\|^2)^\mu, & \|x\| \leq 1 \\ 0, & \text{else,} \end{cases}$$

where $a := \frac{\pi^{\frac{n}{2}} \Gamma(\mu+1)}{\Gamma(\frac{n}{2} + \mu + 1)}$ and $\Gamma: \mathbb{C} \setminus (-\mathbb{N}) \rightarrow \mathbb{C}$ is the gamma function. Then the family $(\psi_{\mu,\varepsilon})_{\varepsilon>0}$ with

$$\psi_{\mu,\varepsilon}(x) := \varepsilon^{-n} \psi_\mu\left(\frac{x}{\varepsilon}\right) \quad \text{for } x \in \mathbb{R}^n \text{ and } \varepsilon > 0$$

is an approximation to the identity in \mathbb{R}^n as well as $(\mathcal{R}\psi_{\mu,\varepsilon}(\theta, \cdot))_{\varepsilon>0}$ in \mathbb{R} for every $\theta \in \mathbb{S}^{n-1}$. Furthermore, the Radon transform of $\psi_{\mu,\varepsilon}$ is given by

$$\mathcal{R}\psi_{\mu,\varepsilon}(\theta, s) = \frac{\Gamma\left(\frac{n}{2} + \mu + 1\right)}{\varepsilon \sqrt{\pi} \Gamma\left(\frac{n-1}{2} + \mu + 1\right)} \left(1 - \frac{s^2}{\varepsilon^2}\right)^{\frac{n-3}{2} + \mu + 1} \quad (2.1)$$

for $(\theta, s) \in \mathbb{S}^{n-1} \times (-\varepsilon, \varepsilon)$ and $\mathcal{R}\psi_{\mu,\varepsilon}(\theta, s) = 0$ for $|s| \geq \varepsilon$.

2.3 Solution of the wave equation

Next, we recall a well-known solution formula for the wave equation (1.1) and deduce other representations which are used for derivation of our general inversion formula in section 3 and 4. From [10] we know that the solution $u: \mathbb{R}^n \times (0, \infty) \rightarrow \mathbb{R}$ of the wave equation with initial data $f, g \in C_c^\infty(\Omega)$ is given by the representation formula

$$u(x, t) = \frac{1}{\gamma_n} \left[\partial_t \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}} \left(\frac{t^n}{\text{vol}(\mathbb{B}^n(x, t))} \int_{\mathbb{B}^n(x, t)} \frac{f(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \right) + \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}} \left(\frac{t^n}{\text{vol}(\mathbb{B}^n(x, t))} \int_{\mathbb{B}^n(x, t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \right) \right] \quad (2.2)$$

for even $n \geq 2$ and $(x, t) \in \mathbb{R}^n \times (0, \infty)$, where $\gamma_n := 2 \cdot 4 \cdot \dots \cdot (n-2) \cdot n$ and $\text{vol}(\mathbb{B}^n(x, t))$ denotes the volume of the n -dimensional ball with center x and radius t . If $n \geq 3$ is odd, then the solution is given by

$$u(x, t) = \frac{1}{\gamma_n} \left[\partial_t \left(\frac{1}{t} \partial_t \right)^{\frac{n-3}{2}} \left(\frac{t^{n-2}}{\sigma(\partial\mathbb{B}^n(x, t))} \int_{\partial\mathbb{B}^n(x, t)} f(y) d\sigma(y) \right) + \left(\frac{1}{t} \partial_t \right)^{\frac{n-3}{2}} \left(\frac{t^{n-2}}{\sigma(\partial\mathbb{B}^n(x, t))} \int_{\partial\mathbb{B}^n(x, t)} g(y) d\sigma(y) \right) \right] \quad (2.3)$$

where $\gamma_n := 1 \cdot 3 \cdot \dots \cdot (n-2)$. In terms of the spherical mean operator, we see that (2.3) can also be represented by

$$u(x, t) = \frac{1}{\gamma_n} \left[\partial_t \left(\frac{1}{t} \partial_t \right)^{\frac{n-3}{2}} \left(t^{n-2} \mathcal{M}f(x, t) \right) + \left(\frac{1}{t} \partial_t \right)^{\frac{n-3}{2}} \left(t^{n-2} \mathcal{M}g(x, t) \right) \right]. \quad (2.4)$$

The next lemma shows another representation of solution formula (2.2) in case of even dimensions.

Lemma 2.2. *Let $n \geq 2$ be an even natural number and $f, g \in C_c^\infty(\Omega)$. Then the representation formulas*

$$u(x, t) = \frac{n}{\gamma_n} \left[\partial_t \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}} \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2 - r^2}} \mathcal{M}f(x, r) dr \right) + \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}} \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2 - r^2}} \mathcal{M}g(x, r) dr \right) \right] \quad (2.5)$$

and

$$u(x, t) = \frac{n}{\gamma_n} \left[\partial_t \left(\int_0^t \frac{r}{\sqrt{t^2 - r^2}} \left(\frac{1}{r} \partial_r \right)^{\frac{n-2}{2}} \left(r^{n-2} \mathcal{M}f(x, r) \right) dr \right) + \left(\int_0^t \frac{r}{\sqrt{t^2 - r^2}} \left(\frac{1}{r} \partial_r \right)^{\frac{n-2}{2}} \left(r^{n-2} \mathcal{M}g(x, r) \right) dr \right) \right] \quad (2.6)$$

for the solution of the wave equation (2.2) with initial data (f, g) hold.

2.4 Key integral identity

Beside the representation formulas (2.4) and (2.6) for the solution of the wave equation, a main ingredient for the derivation of our inversion formulas is the following integral identity for solutions of the wave equation.

Proposition 2.3 (Integral identity for the wave equation). *Let $f, g \in C_c^\infty(\Omega)$. Then the following identity holds:*

$$\int_{\Omega} f(x)g(x) dx = 2 \int_{\partial\Omega} \int_0^\infty v(x, t) \partial_\nu u(x, t) dt d\sigma(x) + \int_{\Omega} \int_0^\infty \Delta(uv)(x, t) dt dx. \quad (2.7)$$

Proof. Let $x \in \Omega$ be a fixed point in the domain. Since u and v are solutions of the wave equation with initial data $(f, 0)$ and $(0, g)$ respectively, we see that application of integration by parts leads to

$$\int_0^\infty v(x, t) \Delta u(x, t) dt = - \int_0^\infty \partial_t u(x, t) \partial_t v(x, t) dt.$$

Then, one further application of integration by parts yields

$$\begin{aligned} - \int_0^\infty \partial_t u(x, t) \partial_t v(x, t) dt &= \lim_{a \searrow 0} u(x, a) \partial_t v(x, a) + \int_0^\infty u(x, t) \Delta v(x, t) dt \\ &= f(x)g(x) + \int_0^\infty u(x, t) \Delta v(x, t) dt \end{aligned}$$

and hence

$$\int_\Omega f(x)g(x)dx = \int_0^\infty \int_\Omega v(x, t) \Delta u(x, t) dt - u(x, t) \Delta v(x, t) dx dt.$$

Next, from Green's second formula we conclude

$$\int_\Omega f(x)g(x)dx = \int_0^\infty \int_{\partial\Omega} v(x, t) \partial_\nu u(x, t) - u(x, t) \partial_\nu v(x, t) d\sigma(x) dt.$$

Since

$$\partial_\nu v(x, t) = \langle \nabla v(x, t), \nu(x) \rangle \text{ and } u(x, t) \nabla v(x, t) = \nabla(uv)(x, t) - v(x, t) \nabla u(x, t)$$

we see that

$$\begin{aligned} \int_\Omega f(x)g(x)dx &= 2 \int_0^\infty \int_{\partial\Omega} v(x, t) \partial_\nu u(x, t) d\sigma(x) dt \\ &\quad + \int_0^\infty \int_{\partial\Omega} \langle \nabla(uv)(x, t), \nu(x) \rangle d\sigma(x) dt. \end{aligned}$$

In the last step, we use the divergence theorem in the second inner integral and change the order of integration afterwards to obtain the desired integral identity. \square

Using the above two auxiliary results, we are now ready to prove the main results of this paper. In the next section, we present our new results for the even-dimensional case.

3 Inversion in even dimension

In this section we derive the inversion formulas for the case of even spatial dimension.

3.1 Statement of the inversion formula

The following theorem is our new result for even dimensions.

Theorem 3.1 (Inversion formula in even dimension). *Let $n \geq 2$ be an even number, $\Omega \subset \mathbb{R}^n$ be a bounded convex domain with smooth boundary and $f \in C_c^\infty(\Omega)$. Then, for every $x \in \Omega$, we have*

$$f(x) = \frac{1}{2^{\frac{n-2}{2}} \pi^{\frac{n}{2}}} (-1)^{\frac{n-2}{2}} \int_{\partial\Omega} \int_{\|x-y\|}^\infty \frac{(\partial_t t^{-1})^{\frac{n-2}{2}} \partial_\nu u(y, t)}{\sqrt{t^2 - \|x-y\|^2}} dt d\sigma(y) + \mathcal{K}_\Omega f(x), \quad (3.1)$$

where

$$\mathcal{K}_\Omega f(x) := \frac{(-1)^{\frac{n-2}{2}}}{2^{n+1}\pi^{n-1}} \int_\Omega f(y) \frac{(\partial_2^n \mathcal{H}_2 \mathcal{R}\chi_\Omega)(\tilde{n}(x,y), \tilde{s}(x,y))}{\|x-y\|^{n-1}} dy$$

and $\tilde{n}(x,y) := (y-x)/\|y-x\|$, $\tilde{s}(x,y) := (\|y\|^2 - \|x\|^2)/(2\|y-x\|)$ for $y \in \Omega$ with $y \neq x$.

Proof. The proof will be given in subsection 3.4. \square

As a consequence of Theorem 3.1 we have the following exact inversion formula for the wave equation from Neumann traces for the case that Ω is an ellipsoid.

Corollary 3.2 (Exact inversion formula for ellipsoids in even dimension). *Let $n \geq 2$ be an even number, $\Omega \subset \mathbb{R}^n$ be an open domain, such that $\partial\Omega$ is an ellipsoid and $f \in C_c^\infty(\Omega)$. Then, for every $x \in \Omega$, we have*

$$f(x) = \frac{1}{2^{\frac{n-2}{2}} \pi^{\frac{n}{2}}} (-1)^{\frac{n-2}{2}} \int_{\partial\Omega} \int_{\|x-y\|}^\infty \frac{\left(\partial_t \frac{1}{t}\right)^{\frac{n-2}{2}} \partial_\nu u(y,t)}{\sqrt{t^2 - \|x-y\|^2}} dt d\sigma(y). \quad (3.2)$$

Proof. From Theorem 3.1 we are left show $\mathcal{K}_\Omega f(x) = 0$ for $x \in \Omega$. This is because of $\partial_2^n \mathcal{H}_2 \mathcal{R}\chi_\Omega = 0$ for the special case where Ω is an elliptical domain as shown in [16]. \square

The proof of Theorem 3.1 requires some preparation. The reconstruction formula (3.1) consists of two terms, where the first term contains the Neumann trace of $u: \mathbb{R}^n \times (0, \infty) \rightarrow \mathbb{R}$ on $\partial\Omega \times (0, \infty)$ and the second term is an integral operator depending on the initial data $f \in C_c^\infty(\Omega)$. Both terms are transformations of the two terms appearing on the right-hand side of the integral identity (2.7). We will derive the inversion formula by manipulating both terms in (2.7) separately.

3.2 Manipulation of the boundary term

The first term on the right-hand side in (2.7) can be computed as follows:

Proposition 3.3. *Let n be an even natural number and $f, g \in C_c^\infty(\Omega)$. Then the identity*

$$\begin{aligned} & \int_0^\infty v(x,t) \partial_\nu u(x,t) dt \\ &= \frac{1}{\omega_n \gamma_n} (-1)^{\frac{n-2}{2}} \int_0^\infty \left(\partial_t \frac{1}{t}\right)^{\frac{n-2}{2}} \partial_\nu u(x,t) \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|y-x\|^2}} dy dt \end{aligned} \quad (3.3)$$

holds for every $x \in \partial\Omega$.

For the proof of this transformation, we need the following lemma.

Lemma 3.4. *Let $n \geq 2$ be a natural number and $g \in C_c^\infty(\Omega)$. Then, for every $k \in \mathbb{N}$ and $(x, t) \in \mathbb{R}^n \times (0, \infty)$ the identity*

$$\begin{aligned} \left(\frac{1}{t}\partial_t\right)^k \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x - y\|^2}} dy &= \sum_{l=0}^k c_{k,l}^{(n)} t^{n-(2k+1-l)} \int_{\mathbb{B}^n(0,1)} \frac{\sum_{i \in \{1, \dots, n\}^k} \partial^i g(x + ty) y^i}{\sqrt{1 - \|y\|^2}} dy \\ &= \sum_{l=0}^k c_{k,l}^{(n)} t^{-(3k-l)} \int_{\mathbb{B}^n(0,t)} \frac{\sum_{i \in \{1, \dots, n\}^k} \partial^i g(x + y) y^i}{\sqrt{t^2 - \|y\|^2}} dy, \end{aligned}$$

holds, where $\partial^i := \partial_{i_1} \dots \partial_{i_k}$, $y^i := y_{i_1} \dots y_{i_k}$ and the coefficients are recursively defined by $c_{1,0}^{(n)} := n - 1$, $c_{1,1}^{(n)} := 1$, $c_{\tilde{k},0}^{(n)} := c_{\tilde{k}-1,0}^{(n)} (n - (2(\tilde{k} - 1) + 1))$, $c_{\tilde{k},\tilde{k}}^{(n)} := 1$ and $c_{\tilde{k},l}^{(n)} := c_{\tilde{k}-1,l-1}^{(n)} + c_{\tilde{k}-1,l}^{(n)} (n - (2(\tilde{k} - 1) - (l - 1)))$ for all $\tilde{k} \in \{2, \dots, k\}$ and $l \in \{1, \dots, \tilde{k} - 1\}$.

Proof. (i) We start the proof by showing

$$\begin{aligned} \left(\frac{1}{t}\partial_t\right)^k \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x - y\|^2}} dy &= \sum_{l=0}^k c_{k,l}^{(n)} t^{n-(2k+1-l)} \partial_t^l \int_{\mathbb{B}^n(0,1)} \frac{g(x + ty)}{\sqrt{1 - \|y\|^2}} dy. \end{aligned} \tag{3.4}$$

For $k = 1$ we follow from the substitution rule

$$\begin{aligned} \frac{1}{t}\partial_t \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x - y\|^2}} dy &= \frac{1}{t}\partial_t t^{n-1} \int_{\mathbb{B}^n(0,1)} \frac{g(x + ty)}{\sqrt{1 - \|y\|^2}} dy \\ &= (n - 1)t^{n-3} \int_{\mathbb{B}^n(0,1)} \frac{g(x + ty)}{\sqrt{1 - \|y\|^2}} dy + t^{n-2}\partial_t \int_{\mathbb{B}^n(0,1)} \frac{g(x + ty)}{\sqrt{1 - \|y\|^2}} dy. \end{aligned}$$

Now suppose that (3.4) holds for any value $k \geq 1$. Hence, our assumption and application of the product rule yield the relation

$$\begin{aligned} \left(\frac{1}{t}\partial_t\right)^{k+1} \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x - y\|^2}} dy &= \frac{1}{t}\partial_t \left(\sum_{l=0}^k c_{k,l}^{(n)} t^{n-(2k+1-l)} \partial_t^l \int_{\mathbb{B}^n(0,1)} \frac{g(x + ty)}{\sqrt{1 - \|y\|^2}} dy \right) \end{aligned}$$

$$\begin{aligned}
 &= \sum_{l=0}^k c_{k,l}^{(n)} (n - (2k + 1 - l)) t^{n-(2(k+1)+1-l)} \partial_t^l \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy \\
 &\quad + c_{k,l}^{(n)} t^{n-(2(k+1)+1-(l+1))} \partial_t^{l+1} \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy,
 \end{aligned}$$

where the last sum can be written as

$$\begin{aligned}
 &c_{k,0}^{(n)} (n - (2k + 1)) t^{n-(2(k+1)+1)} \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy \\
 &\quad + \sum_{l=1}^k \left(c_{k,l}^{(n)} (n - (2k + 1 - l)) + c_{k,l-1}^{(n)} \right) t^{n-(2(k+1)+1-l)} \partial_t^l \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy \\
 &\quad + c_{k,k}^{(n)} t^{n-(2(k+1)+1-(k+1))} \partial_t^{k+1} \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy.
 \end{aligned}$$

Comparing the above coefficients with the coefficients defined in the lemma shows (3.4).

(ii) Differentiating under the integral sign and using the chain rule lead to

$$\partial_t^k \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy = \int_{\mathbb{B}^n(0,1)} \frac{\sum_{i \in \{1, \dots, n\}^k} \partial^i g(x+ty) y^i}{\sqrt{1-\|y\|^2}} dy.$$

Then, substituting y with $\frac{y}{t}$ yields the relation

$$\partial_t^k \int_{\mathbb{B}^n(0,1)} \frac{g(x+ty)}{\sqrt{1-\|y\|^2}} dy = \frac{1}{t^{n+k-1}} \int_{\mathbb{B}^n(0,t)} \frac{\sum_{i \in \{1, \dots, n\}^k} \partial^i g(x+y) y^i}{\sqrt{1-\|y\|^2}} dy,$$

which shows together with (3.4) the desired identity. \square

From Lemma 3.4 we immediately obtain the following corollary.

Corollary 3.5. *Under the assumptions of Lemma 3.4 we have that*

$$\lim_{t \rightarrow \infty} \left(\frac{1}{t} \partial_t \right)^k \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x-y\|^2}} dy = 0 \tag{3.5}$$

and

$$\lim_{t \searrow 0} \frac{1}{t} \left(\partial_t \frac{1}{t} \right)^{\frac{n-2}{2}-m} \partial_\nu u(x,t) \left(\frac{1}{t} \partial_t \right)^m \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x-y\|^2}} dy = 0 \tag{3.6}$$

for all $0 \leq m \leq \frac{n-4}{2}$.

Proof. (i) Since g has compact support in Ω , we can find $R > 0$ such that $\text{supp}(g(x + \cdot)) \subset \mathbb{B}^n(0, R)$. Then, from the previous lemma we have for $t \geq R$

$$\begin{aligned} & \left| \left(\frac{1}{t} \partial_t \right)^k \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x - y\|^2}} dy \right| \\ &= \left| \sum_{l=0}^k c_{k,l}^{(n)} t^{-(3k-l)} \int_{\mathbb{B}^n(0,R)} \frac{\sum_{i \in \{1, \dots, n\}^k} \partial^i g(x+y) y^i}{\sqrt{t^2 - \|y\|^2}} dy \right| \\ &\leq C \sum_{l=0}^k c_{k,l}^{(n)} t^{-(3k-l)} \int_{\mathbb{B}^n(0,R)} \frac{1}{\sqrt{R^2 - \|y\|^2}} dy \\ &= C \sum_{l=0}^k c_{k,l}^{(n)} t^{-(3k-l)} n \omega_n \int_0^R \frac{r^{n-1}}{\sqrt{R^2 - r^2}} dr \\ &= C \sum_{l=0}^k c_{k,l}^{(n)} t^{-(3k-l)} n \omega_n \frac{\sqrt{\pi} R^{n-1} \Gamma(\frac{n}{2})}{2\Gamma(\frac{n+1}{2})} \end{aligned}$$

where we used polar coordinates in the last integral and set

$$C := R^k n^k \max_{i \in \{1, \dots, n\}^k} \max_{y \in \mathbb{R}^n} \left| \partial^i g(y) \right|.$$

This implies Equality (3.5).

(ii) From Lemma 3.4 we conclude that

$$\begin{aligned} & \left| \frac{1}{t} \left(\partial_t \frac{1}{t} \right)^{\frac{n-2}{2}-m} \partial_\nu u(x, t) \left(\frac{1}{t} \partial_t \right)^m \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|x - y\|^2}} dy \right| \\ &\leq D \left| \frac{1}{t} \left(\partial_t \frac{1}{t} \right)^{\frac{n-2}{2}-l} \partial_\nu u(x, t) \right| \left(\sum_{l=0}^m c_{k,l}^{(n)} t^{n-(2m+1-l)} \int_{\mathbb{B}^n(0,1)} \frac{1}{\sqrt{1 - \|y\|^2}} dy \right) \end{aligned}$$

where

$$D := \max_{i \in \{1, \dots, n\}^m} \max_{y \in \mathbb{R}^n} \left| \partial^i g(y) \right|.$$

After applying the product rule on the first factor, we see that the above term consists of variables t with exponents greater than or equal to 2. This observation shows (3.6). \square

Proof of Proposition 3.3. We prove the statement by showing

$$\begin{aligned} & \int_0^\infty v(x, t) \partial_\nu u(x, t) dt \\ &= \frac{1}{\omega_n \gamma_n} (-1)^k \int_0^\infty \left(\partial_t \frac{1}{t} \right)^k \partial_\nu u(x, t) \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}-k} \int_{\mathbb{B}^n(x,t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \end{aligned}$$

for all $1 \leq k \leq \frac{n-2}{2}$. For $k = 1$, inserting representation formula (2.2) for v and applying integration by parts yield the relation

$$\begin{aligned} & \int_0^\infty v(x, t) \partial_\nu u(x, t) dt \\ &= \frac{1}{\omega_n \gamma_n} \left(\lim_{a \searrow 0} \int_a^c \frac{1}{t} \partial_\nu u(x, t) \partial_t \left(\frac{1}{t} \partial_t \right)^{\frac{n-4}{2}} \int_{\mathbb{B}^n(x, t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \right. \\ & \quad \left. + \lim_{b \rightarrow \infty} \int_c^b \frac{1}{t} \partial_\nu u(x, t) \partial_t \left(\frac{1}{t} \partial_t \right)^{\frac{n-4}{2}} \int_{\mathbb{B}^n(x, t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \right) \\ &= -\frac{1}{\omega_n \gamma_n} \int_0^\infty \partial_t \frac{1}{t} \partial_\nu u(x, t) \left(\frac{1}{t} \partial_t \right)^{\frac{n-4}{2}} \int_{\mathbb{B}^n(x, t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \end{aligned}$$

for some $c \in (0, \infty)$, where the boundary term is zero because of (3.5) and (3.6). Now, suppose that the above identity holds for any value $1 \leq k < \frac{n-2}{2}$. Then, by using the same arguments as before we obtain

$$\begin{aligned} & \int_0^\infty v(x, t) \partial_\nu u(x, t) dt \\ &= \frac{(-1)^k}{\omega_n \gamma_n} \int_0^\infty \left(\partial_t \frac{1}{t} \right)^k \partial_\nu u(x, t) \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}-k} \int_{\mathbb{B}^n(x, t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy \\ &= \frac{(-1)^{k+1}}{\omega_n \gamma_n} \int_0^\infty \left(\partial_t \frac{1}{t} \right)^{k+1} \partial_\nu u(x, t) \left(\frac{1}{t} \partial_t \right)^{\frac{n-2}{2}-(k+1)} \int_{\mathbb{B}^n(x, t)} \frac{g(y)}{\sqrt{t^2 - \|y - x\|^2}} dy, \end{aligned}$$

which finally proves our desired transformation. \square

3.3 Manipulation of the interior term

In this section we derive a relation that allows to reformulate (2.7) such that the interior term can be seen to vanish for special domains Ω . This transformation requires a lot of calculations. We therefore separate the proof in several parts in order to structure the proof better for the reader.

The first lemma reads as follows:

Lemma 3.6. *Let $n \geq 2$ be an even natural number and $f, g \in C_c^\infty(\Omega)$. Then, for every $x \in \Omega$ we have*

$$\begin{aligned} & \int_0^\infty u(x, t) v(x, t) dt \\ &= -\frac{n}{\gamma_n} \int_0^\infty f(x) r_2 \mathcal{D}_{r_2} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \log r_2 dr_2 \\ & \quad - \frac{n^2}{2\gamma_n^2} \int_0^\infty \int_0^\infty \partial_{r_1} \mathcal{D}_{r_1}^{\frac{n-2}{2}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) r_2 \\ & \quad \cdot \mathcal{D}_2^{\frac{n-2}{2}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \log |r_2^2 - r_1^2| dr_2 dr_1, \end{aligned} \tag{3.7}$$

where $\mathcal{D}_r := \frac{1}{r} \partial_r$.

Proof. (i) Let T be a fixed positive number greater than the diameter of Ω . Using representation formula (2.6) and applying integration by parts lead to

$$\begin{aligned} & \int_0^T u(x, t) v(x, t) dt \\ &= \frac{n^2}{\gamma_n^2} \int_0^T \partial_t \left(\int_0^t \frac{r_1}{\sqrt{t^2 - r_1^2}} \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) dr_1 \right) \\ & \quad \cdot \int_0^t \frac{r_2}{\sqrt{t^2 - r_2^2}} \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) dr_2 dt \\ &= \frac{n^2}{\gamma_n^2} \int_0^T \partial_t \left(t \frac{\gamma_n}{n} f(x) + \int_0^t \sqrt{t^2 - r_1^2} \partial_{r_1} \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) dr_1 \right) \\ & \quad \cdot \int_0^t \frac{r_2}{\sqrt{t^2 - r_2^2}} \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) dr_2 dt \end{aligned}$$

which, according to Leibniz's integral rule, can be further be written as

$$\begin{aligned} & \int_0^T f(x) v(x, t) dt + \frac{n^2}{\gamma_n^2} \int_0^T \int_0^t \int_0^t \frac{tr_2}{\sqrt{t^2 - r_1^2} \sqrt{t^2 - r_2^2}} \\ & \quad \cdot \partial_{r_1} \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) dr_2 dr_1 dt . \end{aligned}$$

From

$$\partial_t \log \left(\sqrt{t^2 - r_2^2} + \sqrt{t^2 - r_1^2} \right) = \frac{t}{\sqrt{t^2 - r_1^2} \sqrt{t^2 - r_2^2}}$$

we see that the right triple integral is equal to

$$\begin{aligned} & \frac{n^2}{\gamma_n^2} \int_0^T \partial_{r_1} \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) \int_0^T r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \\ & \quad \cdot \int_{\max\{r_1, r_2\}}^t \frac{t}{\sqrt{t^2 - r_1^2} \sqrt{t^2 - r_2^2}} dt dr_2 dr_1 \\ &= \frac{n^2}{\gamma_n^2} \int_0^T \int_0^T \partial_{r_1} \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \\ & \quad \cdot \log \left(\sqrt{T^2 - r_2^2} + \sqrt{T^2 - r_1^2} \right) dr_2 dr_1 \\ & \quad - \frac{n^2}{2\gamma_n^2} \int_0^T \int_0^T \partial_{r_1} \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \\ & \quad \cdot \log \left| r_2^2 - r_1^2 \right| dr_2 dr_1 \end{aligned}$$

after changing the order of the integrals.

(ii) We further observe that the above first double integral on the right-hand side can be written as

$$\begin{aligned}
 & -\frac{n}{\gamma_n} \int_0^T f(x) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \log \left(T + \sqrt{T^2 - r_2^2} \right) dr_2 \\
 & \quad + \frac{n^2}{\gamma_n^2} \int_0^T \int_0^T \mathcal{D}_{r_1^{\frac{n-2}{2}}} \left(r_1^{n-2} \mathcal{M}f(x, r_1) \right) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \\
 & \quad \cdot \frac{r_1}{\left(\sqrt{T^2 - r_1^2} + \sqrt{T^2 - r_2^2} \right) \sqrt{T^2 - r_1^2}} dr_1 dr_2,
 \end{aligned}$$

by a further application of integration by parts, whereby the first term can be expressed as

$$\begin{aligned}
 & -\frac{n}{\gamma_n} \int_0^\infty f(x) \int_{r_2}^T \frac{r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right)}{\sqrt{t^2 - r_2^2}} dt dr_2 \\
 & \quad - \frac{n}{\gamma_n} \int_0^T f(x) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \log(r_2) dr_2.
 \end{aligned}$$

From Fubini's theorem and solution formula (2.6) we can conclude that this term corresponds to

$$- \int_0^\infty f(x) v(x, t) dt - \frac{n}{\gamma_n} \int_0^T f(x) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2) \right) \log(r_2) dr_2.$$

Finally Items (i) and (ii) and letting $T \rightarrow \infty$ lead to the desired identity. \square

Based on Lemma 3.6, we can now prove the following statement:

Lemma 3.7. *Under the assumptions of Lemma 3.6 we have that*

$$\begin{aligned}
 & \int_\Omega \int_0^\infty u(x, t) v(x, t) dt dx \\
 & = \frac{(-1)^{\frac{n}{2}} 2^{n-2} n^2}{\gamma_n^2} \lim_{m, k \rightarrow \infty} \int_{\mathbb{R}^n} \int_0^\infty \int_0^\infty \varphi_m(x) r_1^{n-1} r_2^{n-1} \mathcal{M}f(x, r_1) \mathcal{M}g(x, r_2) \\
 & \quad \cdot \Phi_k^{(n-1)}(r_2^2 - r_1^2) dr_2 dr_1 dx
 \end{aligned}$$

where $(\varphi_m)_{m \in \mathbb{N}}$ is a family of bounded and integrable functions converging pointwise to χ_Ω and $(\Phi_k)_{k \in \mathbb{N}}$ a family of smooth functions converging pointwise to $\log|\cdot|$ almost everywhere. Here, we set for short $\lim_{m, k \rightarrow \infty}$ as $\lim_{m \rightarrow \infty} \lim_{k \rightarrow \infty}$.

Proof. (i) We first show

$$\int_\Omega \int_0^\infty \int_0^\infty \partial_{r_1} \mathcal{D}_{r_1^{\frac{n-2}{2}}} r_1^{n-2} \mathcal{M}f(x, r_1) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} r_2^{n-2} \mathcal{M}g(x, r_2) \log|r_2^2 - r_1^2| dr_2 dr_1 dx$$

$$\begin{aligned}
&= \lim_{m,k \rightarrow \infty} \left[\frac{(-1)^{\frac{n}{2}} 2^{\frac{n-2}{2}} \gamma_n}{n} \int_{\mathbb{R}^n} \int_0^\infty \varphi_m(x) f(x) r_2^{n-1} \mathcal{M}g(x, r_2) \Phi_k^{\left(\frac{n-2}{2}\right)}(r_2^2) dr_2 dx \right. \\
&\quad \left. + (-1)^{\frac{n-2}{2}} 2^{n-1} \int_{\mathbb{R}^n} \int_0^\infty \int_0^\infty \varphi_m(x) r_1^{n-1} r_2^{n-1} \mathcal{M}f(x, r_1) \mathcal{M}g(x, r_2) \right. \\
&\quad \left. \cdot \Phi_k^{(n-1)}(r_2^2 - r_1^2) dr_2 dr_1 dx \right]
\end{aligned}$$

for all $x \in \Omega$. For that purpose, we apply Lebesgue's dominated convergence theorem to deduce

$$\begin{aligned}
&\int_\Omega \int_0^\infty \int_0^\infty \partial_{r_1} \mathcal{D}_{r_1}^{\frac{n-2}{2}} r_1^{n-2} \mathcal{M}f(x, r_1) r_2 \mathcal{D}_2^{\frac{n-2}{2}} r_2^{n-2} \mathcal{M}g(x, r_2) \\
&\quad \cdot \log |r_2^2 - r_1^2| dr_2 dr_1 dx \\
&= \lim_{k,m \rightarrow \infty} \left[\int_{\mathbb{R}^n} \int_0^\infty \int_0^\infty \varphi_m(x) \partial_{r_1} \mathcal{D}_{r_1}^{\frac{n-2}{2}}(r_1^{n-2} \mathcal{M}f(x, r_1)) \right. \\
&\quad \left. \cdot r_2 \mathcal{D}_2^{\frac{n-2}{2}}(r_2^{n-2} \mathcal{M}g(x, r_2)) \Phi_k(r_2^2 - r_1^2) dr_2 dr_1 dx \right]. \tag{3.8}
\end{aligned}$$

Furthermore, application of integration $\frac{n-2}{2}$ -times with respect to r_2 gives us

$$\begin{aligned}
&\int_0^\infty \int_0^\infty \partial_{r_1} \mathcal{D}_{r_1}^{\frac{n-2}{2}}(r_1^{n-2} \mathcal{M}f(x, r_1)) r_2 \mathcal{D}_2^{\frac{n-2}{2}}(r_2^{n-2} \mathcal{M}g(x, r_2)) \Phi_k(r_2^2 - r_1^2) dr_2 dr_1 \\
&= (-2)^{\frac{n-2}{2}} \int_0^\infty \int_0^\infty \partial_{r_1} \mathcal{D}_{r_1}^{\frac{n-2}{2}}(r_1^{n-2} \mathcal{M}f(x, r_1)) r_2^{n-1} \mathcal{M}g(x, r_2) \\
&\quad \cdot \Phi_k^{\left(\frac{n-2}{2}\right)}(r_2^2 - r_1^2) dr_2 dr_1,
\end{aligned}$$

where changing the order of integration and partial integration with respect r_1 lead then to

$$\begin{aligned}
&\frac{(-1)^{\frac{n}{2}} 2^{\frac{n-2}{2}} \gamma_n}{n} \int_0^\infty f(x) r_2^{n-1} \mathcal{M}g(x, r_2) \Phi_k^{\left(\frac{n-2}{2}\right)}(r_2^2) dr_2 \\
&\quad + (-1)^{\frac{n-2}{2}} 2^{\frac{n}{2}} \int_0^\infty \int_0^\infty \mathcal{D}_{r_1}^{\frac{n-2}{2}}(r_1^{n-2} \mathcal{M}f(x, r_1)) r_2^{n-1} \mathcal{M}g(x, r_2) \\
&\quad \cdot \Phi_k^{\left(\frac{n}{2}\right)}(r_2^2 - r_1^2) dr_2 dr_1.
\end{aligned}$$

Finally, the application of integration by parts formula $\frac{n-4}{2}$ -times with respect to variable r_1 shows together with (3.8) the above identity.

(ii) In the last step we apply partial integration $\frac{n-2}{2}$ -times on the first term to obtain the relation

$$\int_0^\infty \varphi_m(x) f(x) r_2^{n-1} \mathcal{M}g(x, r_2) \Phi_k^{\left(\frac{n-2}{2}\right)}(r_2^2) dr_2$$

$$= \left(-\frac{1}{2}\right)^{\frac{n-2}{2}} \int_0^\infty \varphi_m(x) f(x) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2)\right) \Phi_k \left(r_2^2\right) dr_2.$$

for $m, k \in \mathbb{N}$. Thus, by applying Lebesgue's dominated convergence theorem we have

$$\begin{aligned} \lim_{m, k \rightarrow \infty} \left[\frac{(-1)^{\frac{n}{2}} 2^{\frac{n-2}{2}} \gamma_n}{n} \int_{\mathbb{R}^n} \int_0^\infty \varphi_m(x) f(x) r_2^{n-1} \mathcal{M}g(x, r_2) \Phi_k^{\left(\frac{n-2}{2}\right)} \left(r_2^2\right) dr_2 \right] \\ = -\frac{2\gamma_n}{n} \int_{\Omega} \int_0^\infty f(x) r_2 \mathcal{D}_{r_2^{\frac{n-2}{2}}} \left(r_2^{n-2} \mathcal{M}g(x, r_2)\right) \log r_2 dr_2 dx, \end{aligned}$$

which shows the claimed identity by using Lemma 3.6 and (i). \square

Now, we are ready to reshape the above double integral into our final transformation.

Proposition 3.8. *The left double integral in Lemma 3.7 can be finally transformed to*

$$\begin{aligned} \int_{\Omega} \int_0^\infty u(x, t) v(x, t) dt dx \\ = \frac{(-1)^{\frac{n-2}{2}}}{2^{n+1} \pi^{n-1}} \int_{\Omega} g(x) \int_{\Omega} f(y) \frac{\left(\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \chi_{\Omega}\right) (\tilde{n}(x, y), \tilde{s}(x, y))}{\|x - y\|^{n-1}} dy dx. \end{aligned}$$

Proof. In the following, we use the approximation of identity $(\psi_{\mu, \frac{1}{m}})_{m \in \mathbb{N}}$ from Lemma 2.1 with $\mu = \frac{n}{2} + 1$ and set $\varphi_m := \chi_{\Omega} * \psi_{\mu, \frac{1}{m}}$ for $m \in \mathbb{N}$. Hence, from the properties of the convolution operator and Lemma 2.1 we see that the family $(\varphi_m)_{m \in \mathbb{N}}$ satisfies the assumption in Lemma 3.7 and $\varphi_m \in C_c^n(\mathbb{R}^n)$ as well as $\mathcal{R}\varphi_m(\theta, \cdot) \in C_c^n(\mathbb{R})$ for every $\theta \in \mathbb{S}^{n-1}$.

(i) In the first step of the proof we show

$$\begin{aligned} \int_{\Omega} \int_0^\infty u(x, t) v(x, t) dt dx \\ = \frac{(-1)^{\frac{n-2}{2}}}{2^{n+1} \pi^{n-1}} \lim_{m \rightarrow \infty} \int_{\Omega} g(x) \int_{\Omega} f(y) \frac{\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \varphi_m (\tilde{n}(x, y), \tilde{s}(x, y))}{\|x - y\|^{n-1}} dy dx. \end{aligned}$$

We observe that the right triple integral in Lemma 3.7 inside the limit equals

$$\begin{aligned} \int_{\mathbb{R}^n} \int_0^\infty \int_0^\infty \varphi_m(x) r_1^{n-1} r_2^{n-1} \mathcal{M}f(x, r_1) \mathcal{M}g(x, r_2) \Phi_k^{(n-1)}(r_2^2 - r_1^2) dr_2 dr_1 dx \\ = \frac{1}{n^2 \omega_n^2} \int_{\mathbb{R}^n} \int_{\Omega} \int_{\Omega} \varphi_m(x) g(y) f(z) \Phi_k^{(n-1)}(\|x - y\|^2 - \|x - z\|^2) dz dy dx \end{aligned}$$

by using polar coordinates and substitution rule. Furthermore, Fubini's theorem and the relation

$$\|x - y\|^2 - \|x - z\|^2 = 2 \langle z - y, x - (z + y)/2 \rangle$$

give us

$$\frac{1}{n^2 \omega_n^2} \int_{\Omega} g(y) \int_{\Omega} f(z) \int_{\mathbb{R}^n} \varphi_m(x) \Phi_k^{(n-1)}(2 \langle z - y, x - (z + y)/2 \rangle) dx dz dy. \quad (3.9)$$

Next, we apply the substitution rule with the diffeomorphism

$$h_{y,z}: \mathbb{R}^n \rightarrow \mathbb{R}^n: (s, x_1, \dots, x_{n-1}) \mapsto s \tilde{n}(y, z) + \sum_{i=1}^{n-1} x_i \theta_i,$$

where $(\tilde{n}(y, z), \theta_1, \dots, \theta_{n-1})$ is an orthonormal basis of \mathbb{R}^n , and Fubini's theorem on the inner integral in (3.9) to obtain

$$\begin{aligned} & \int_{\mathbb{R}^n} \varphi_m(x) \Phi_k^{(n-1)}(2 \langle z - y, x - (z + y)/2 \rangle) dx \\ &= \int_{\mathbb{R}} \int_{\mathbb{R}^{n-1}} \varphi_m(h_{y,z}(s, x)) \Phi_k^{(n-1)}(2 \langle z - y, h_{y,z}(s, x) - (z + y)/2 \rangle) dx ds. \end{aligned}$$

Since $z - y$ is orthogonal to $\theta_1, \dots, \theta_{n-1}$ we have

$$\begin{aligned} & \int_{\mathbb{R}^n} \varphi_m(x) \Phi_k^{(n-1)}(2 \langle z - y, x - (z + y)/2 \rangle) dx \\ &= \int_{\mathbb{R}} \int_{\mathbb{R}^{n-1}} \varphi_m(h_{y,z}(s, x)) \Phi_k^{(n-1)}(\langle z - y, s \tilde{n}(y, z) - (z + y)/2 \rangle) dx ds \\ &= \int_{\mathbb{R}} \int_{\mathbb{R}^{n-1}} \varphi_m(h_{y,z}(s, x)) \Phi_k^{(n-1)}(2 \|z - y\| (s - \tilde{s}(y, z))) dx ds \\ &= \int_{\mathbb{R}} \mathcal{R} \varphi_m(\tilde{n}(y, z), s) \Phi_k^{(n-1)}(2 \|z - y\| (s - \tilde{s}(y, z))) ds \\ &= \frac{(-1)^{n-1}}{2^{n-1} \|z - y\|^{n-1}} \int_{\mathbb{R}} \partial_2^{n-1} \mathcal{R} \varphi_m(\tilde{n}(y, z), s) \Phi_k(2 \|z - y\| (s - \tilde{s}(y, z))) ds, \end{aligned}$$

where we applied partial integration $n - 1$ -times in the last step. Moreover, by choosing $(\Phi_n)_{n \in \mathbb{N}}$ such that $|\Phi_n| \leq |\log |\cdot||$ for all $n \in \mathbb{N}$ we deduce from the estimate

$$\begin{aligned} & \int_{\Omega} \int_{\Omega} \int_{\mathbb{R}} \left| \frac{g(y)f(z)}{\|z - y\|^{n-1}} \partial_2^{n-1} \mathcal{R} \varphi_m(\tilde{n}(y, z), s) \Phi_k(2 \|z - y\| (s - \tilde{s}(y, z))) \right| ds dz dy \\ & \leq \int_{\Omega} \int_{\Omega} \frac{|g(y)f(z)|}{\|z - y\|^{n-1}} \int_{\mathbb{R}} \left| \partial_2^{n-1} \mathcal{R} \varphi_m(\tilde{n}(y, z), s + \tilde{s}(y, z)) \right| \\ & \quad \cdot (|\log |2 \|z - y\|| + |\log |s||) ds dz dy < \infty, \end{aligned}$$

Lebesgue's theorem and Lemma 3.7

$$\begin{aligned} & \int_{\Omega} \int_0^{\infty} u(x, t) v(x, t) dt dx \\ &= \frac{(-1)^{\frac{n-2}{2}}}{2 \gamma_n^2 \omega_n^2} \lim_{m \rightarrow \infty} \int_{\Omega} g(y) \int_{\Omega} \frac{f(z)}{\|z - y\|^{n-1}} \end{aligned}$$

$$\cdot \int_{\mathbb{R}} \partial_2^{n-1} \mathcal{R}\varphi_m(\tilde{n}(y, z), s) \log |2 \|z - y\| (s - \tilde{s}(y, z))| ds dz dy.$$

Furthermore, application of integration by parts to the inner integral yields

$$\begin{aligned} \int_{\mathbb{R}} \partial_2^{n-1} \mathcal{R}\varphi_m(\tilde{n}(y, z), s) \log |2 \|z - y\| (s - \tilde{s}(y, z))| ds \\ = \lim_{\delta \searrow 0} \int_{\mathbb{R} \setminus (\tilde{s} - \delta, \tilde{s} + \delta)} \frac{\partial_2^{n-2} \mathcal{R}\varphi_m(\tilde{n}(y, z), s)}{\tilde{s}(y, z) - s} ds \\ = \pi \mathcal{H}_2 \partial_2^{n-2} \mathcal{R}\varphi_m(\tilde{n}(y, z), \tilde{s}(y, z)), \end{aligned}$$

where we set for short $\tilde{s} = \tilde{s}(y, z)$. Hence, the equalities $\gamma_n = 2^{n/2} (\frac{n}{2})!$ and $\omega_n = \pi^{n/2} / \Gamma(\frac{n}{2} + 1) = \pi^{n/2} / (\frac{n}{2})!$ show the above identity.

(ii) Because Ω is smooth and convex, the Radon transform $\mathcal{R}\chi_\Omega$ is smooth on the set $A = \{(\theta, s) \in \mathbb{S}^{n-1} \times \mathbb{R} \mid E(\theta, s) \cap \Omega \neq \emptyset\}$. As the Hilbert transform is the distributional convolution with the principal value distribution P. V. $1/s$, its Hilbert transform $\mathcal{H}_2 \mathcal{R}\chi_\Omega$ is smooth on the set A , too (see, for example, [9]).

(iii) Next, we define the set $\Omega_0 := \{x \in \Omega \mid \text{dist}(x, \partial\Omega) > \rho\}$ and $A_0 = \{(\theta, s) \in \mathbb{S}^{n-1} \times \mathbb{R} \mid E(\theta, s) \cap \Omega_0 \neq \emptyset\}$, where $\rho := \text{dist}(\text{supp}(f) \cup \text{supp}(g), \partial\Omega)/2$. Since Ω is convex, we have that Ω_0 is convex.

From the properties of the Radon transform we have $\mathcal{R}\varphi_m = \mathcal{R}\chi_\Omega *_2 \mathcal{R}\psi_m$, where we set for short $\psi_m := \psi_{\mu, \frac{1}{m}}$. Since $\mathcal{R}\chi_\Omega(\theta, \cdot) \in L^2(\mathbb{R})$, we deduce from the boundedness of the Hilbert transform $\mathcal{H}: L^2(\mathbb{R}) \rightarrow L^2(\mathbb{R})$ and Young's inequality the relation $\mathcal{H}_2 \mathcal{R}\varphi_m = (\mathcal{H}_2 \mathcal{R}\chi_\Omega) *_2 \mathcal{R}\psi_m$. Moreover, there exists $M \in \mathbb{N}$ such that for all $m \geq M$ $\text{supp}(\mathcal{R}\psi_m(\theta, \cdot)) \leq \text{dist}(\overline{\Omega_0}, \partial\Omega)$ for a fixed angle $\theta \in \mathbb{S}^{n-1}$. Thus, Item (ii) implies that for all $m \geq M$ the function $h_\theta(\cdot, y)$ with

$$h_\theta: \{s \in \mathbb{R} \mid (\theta, s) \in A_0\} \times \mathbb{R} \rightarrow \mathbb{R}: (s, y) \mapsto (\mathcal{H}_2 \mathcal{R}\chi_\Omega)(\theta, s - y) \mathcal{R}\psi(\theta, y)$$

is smooth for all $y \in \mathbb{R}$ where

$$\partial_2^{n-2} h_\theta(s, y) = \begin{cases} \partial_2^{n-2} \mathcal{H}_2 \mathcal{R}\chi_\Omega(\theta, s - y) \mathcal{R}\psi_m(\theta, y), & y \in \text{supp}(\mathcal{R}\psi_m(\theta, \cdot)) \\ 0, & \text{else} \end{cases}$$

and

$$\left| \partial_2^{n-2} h_\theta(s, y) \right| \leq \max \left\{ \left| \partial_2^{n-2} \mathcal{H}_2 \mathcal{R}\chi_\Omega(\tilde{\theta}, \tilde{s}) \right| \mid (\tilde{\theta}, \tilde{s}) \in \overline{A_0} \right\} |\mathcal{R}\psi_m(\theta, y)|.$$

It then follows from the theorem on the parametrized integrals that for all $(\theta, s) \in A_0$

$$\begin{aligned} \partial_2^{n-1} (\mathcal{H}_2 \mathcal{R}\chi_\Omega) *_2 \mathcal{R}\psi_m(\theta, s) &= \partial_2^{n-1} \int_{\mathbb{R}} h_\theta(s, y) dy \\ &= \int_{\mathbb{R}} \partial_2^{n-2} \mathcal{H}_2 \mathcal{R}\chi_\Omega(\theta, s - y) \mathcal{R}\psi_m(\theta, y) dy \\ &= ((\partial_2^{n-1} \mathcal{H}_2 \mathcal{R}\chi_\Omega) *_2 \mathcal{R}\psi_m)(\theta, s). \end{aligned}$$

Hence, Lemma 2.1 implies that $\partial_2^{n-2}\mathcal{H}_2\mathcal{R}\varphi_m$ converges uniformly to $\partial_2^{n-2}\mathcal{H}_2\mathcal{R}\chi_\Omega$ on the closed set $\overline{A_0}$. Since $(\tilde{n}(x, y), \tilde{s}(x, y)) \in A_0$ for all $x, y \in \Omega$, we finally obtain the desired transformation from (i). \square

3.4 Proof of Theorem 3.1

Because of Proposition 3.3 we have

$$\begin{aligned} & \int_{\partial\Omega} \int_0^\infty v(y, t) \partial_\nu u(y, t) dt d\sigma(y) \\ &= \frac{1}{\omega_n \gamma_n} (-1)^{\frac{n-2}{2}} \int_{\partial\Omega} \int_0^\infty \int_{\mathbb{R}^n} \left(\partial_t \frac{1}{t} \right)^{\frac{n-2}{2}} \partial_\nu u(y, t) \frac{g(x) \chi_{(0,t)}(\|x-y\|)}{\sqrt{t^2 - \|x-y\|^2}} dx dt d\sigma(y) \\ &= \frac{1}{\omega_n \gamma_n} (-1)^{\frac{n-2}{2}} \int_\Omega g(x) \int_{\partial\Omega} \int_{\|x-y\|}^\infty \frac{\left(\partial_t \frac{1}{t} \right)^{\frac{n-2}{2}} \partial_\nu u(y, t)}{\sqrt{t^2 - \|x-y\|^2}} dt d\sigma(y) dx. \end{aligned} \quad (3.10)$$

Next we show that

$$\begin{aligned} & \int_\Omega \int_0^\infty \Delta(uv)(x, t) dt dx \\ &= \frac{(-1)^{\frac{n-2}{2}}}{2^{n+1} \pi^{n-1}} \int_\Omega g(x) \int_\Omega f(y) \frac{(\partial_2^n \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(x, y), \tilde{s}(x, y))}{\|x-y\|^{n-1}} dy \end{aligned} \quad (3.11)$$

for every test function $g \in C_c^\infty(\Omega)$.

Since Δu and Δv are solutions of the wave equation with initial data $(\Delta f, 0)$ and $(0, \Delta g)$, respectively, as well as ∇u and ∇v with respect to $(\nabla f, 0)$ and $(0, \nabla g)$, from Proposition 3.8 and the relation $\Delta uv = v\Delta u + 2\langle \nabla u, \nabla v \rangle + u\Delta v$ it follows that

$$\begin{aligned} & \int_\Omega \int_0^\infty \Delta(uv)(x, t) dt dx \\ &= \frac{(-1)^{\frac{n-2}{2}}}{2^{n+1} \pi^{n-1}} \int_\Omega \int_\Omega \left(\Delta f(y)g(x) + 2 \sum_{i=1}^n \partial_i f(y) \partial_i g(x) + f(y) \Delta g(x) \right) \\ & \quad \cdot \frac{(\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(x, y), \tilde{s}(x, y))}{\|x-y\|^{n-1}} dy dx. \end{aligned}$$

The application of the substitution rule on the double integral with the diffeomorphism $\Phi: X \rightarrow \Omega \times \Omega: (p, q) \mapsto (p, p-q)$, where $X := \{(x, x-y) \mid x, y \in \Omega\}$ leads to

$$\begin{aligned} & \int_X \left(\Delta f(p-q)g(p) + 2 \sum_{i=1}^n \partial_i f(p-q) \partial_i g(p) + f(p-q) \Delta g(p) \right) \\ & \quad \cdot \frac{(\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(p, p-q), \tilde{s}(p, p-q))}{\|q\|^{n-1}} d(p, q) \end{aligned}$$

$$\begin{aligned}
&= \int_X \sum_{i=1}^n \partial_i^2 (f \circ (\pi_1 - \pi_2) \cdot g \circ \pi_1)(p, q) \\
&\quad \cdot \frac{(\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(p, p-q), \tilde{s}(p, p-q))}{\|q\|^{n-1}} d(p, q) \\
&= \int_{\pi_2(X)} \int_{X^{[q]}} \sum_{i=1}^n \partial_i^2 (f \circ (\pi_1 - \pi_2) \cdot g \circ \pi_1)(p, q) \\
&\quad \cdot \frac{(\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(p, p-q), \tilde{s}(p, p-q))}{\|q\|^{n-1}} dp dq,
\end{aligned}$$

where $\pi_1: (x, y) \mapsto x$, $\pi_2: (x, y) \mapsto y$ and $X^{[q]} := \{p \in \mathbb{R}^n \mid (p, q) \in X\}$ for $q \in \pi_2(X)$. From partial integration and the chain rule it then follows that the double integral equals

$$\begin{aligned}
&\int_{\pi_2(X)} \int_{X^{[q]}} f(p-q)g(p) \sum_{i=1}^n \partial_i^2 \frac{(\partial_2^{n-2} \mathcal{H}_2 \mathcal{R} \chi_\Omega)(-q/\|q\|, \tilde{s}(p, p-q))}{\|q\|^{n-1}} dp dq \\
&= \int_{\pi_2(X)} \int_{X^{[q]}} f(p-q)g(p) \sum_{i=1}^n \frac{(\partial_2^n \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(p, p-q), \tilde{s}(p, p-q)) q_i^2}{\|q\|^{n+1}} dp dq \\
&= \int_{\pi_2(X)} \int_{X^{[q]}} f(p-q)g(p) \frac{(\partial_2^n \mathcal{H}_2 \mathcal{R} \chi_\Omega)(\tilde{n}(p, p-q), \tilde{s}(p, p-q))}{\|q\|^{n-1}} dp dq
\end{aligned}$$

One further application of the substitution rule with Φ^{-1} shows (3.11).

Finally, from Proposition 2.3 and equations (3.10) and (3.11) we have

$$\begin{aligned}
&\int_\Omega f(x)g(x) \\
&= \int_\Omega g(x) \left(\frac{(-1)^{\frac{n-2}{2}}}{2^{\frac{n-2}{2}} \pi^{\frac{n}{2}}} \int_{\partial\Omega} \int_{\|x-y\|}^\infty \frac{(\partial_t \frac{1}{t})^{\frac{n-2}{2}} \partial_\nu u(y, t)}{\sqrt{t^2 - \|x-y\|^2}} dt d\sigma(y) + \mathcal{K}_\Omega f(x) \right) dx
\end{aligned}$$

for every test function $g \in C_c^\infty(\Omega)$, which shows the claimed inversion formula in even dimension.

4 Inversion in odd dimension

4.1 The inversion formulas

The following theorem is our main result for odd dimensions.

Theorem 4.1 (Inversion formula in odd dimension). *Let $n \geq 3$ be an odd number, $\Omega \subset \mathbb{R}^n$ be a bounded convex domain with smooth boundary and $f \in C_c^\infty(\Omega)$. Then, for*

every $x \in \Omega$, we have

$$f(x) = \frac{1}{(2\pi)^{\frac{n-1}{2}}} (-1)^{\frac{n-3}{2}} \int_{\partial\Omega} \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(y, \|x-y\|) d\sigma(y) + \mathcal{K}_\Omega f(x), \quad (4.1)$$

where

$$\mathcal{K}_\Omega f(x) := \frac{(-1)^{\frac{n-3}{2}}}{2^{n+1} \pi^{n-1}} \int_\Omega f(y) \frac{(\partial_2^n \mathcal{R}\chi_\Omega)(\tilde{n}(x,y), \tilde{s}(x,y))}{\|x-y\|^{n-1}} dy.$$

Proof. The proof will be given in subsection 4.4. \square

Similar to the even dimensional case as a consequence of Theorem 4.1 we derive the following exact inversion for the case that Ω is an elliptical domain of the form $\{x \in \mathbb{R}^n \mid \|Qx\| < 1\}$ for some invertible matrix $Q \in \mathbb{R}^{n \times n}$.

Corollary 4.2 (Exact inversion formula for ellipsoids in odd dimension). *Let $n \geq 3$ be an odd number, $\Omega \subset \mathbb{R}^n$ be an elliptical domain and $f \in C_c^\infty(\Omega)$. Then, for every $x \in \Omega$, we have*

$$f(x) = \frac{1}{(2\pi)^{\frac{n-1}{2}}} (-1)^{\frac{n-3}{2}} \int_{\partial\Omega} \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(y, \|x-y\|) d\sigma(y). \quad (4.2)$$

Proof. Because of Theorem 4.1 we are left to show that $\mathcal{K}_\Omega f(x) = 0$ for $x \in \Omega$ as in even dimension. We refer again to [16], where the identity $\partial_2^n \mathcal{R}\chi_\Omega = 0$ in odd dimension has been verified. \square

For the derivation of the above explicit inversion formula we follow the same strategy as in even dimension. We prove similar Lemmas by using now solution formula (2.3) and make use of some parts of the proofs in even dimension. We will also see that the proof of Theorem 4.1 is shorter than the proof in even dimension. One reason for this is that solution of the wave equation in odd dimension has a simpler form than in the even case. On the other hand, the solution of the wave equation has compact support in the time domain for each fixed point when the initial data has compact support.

4.2 Manipulation of the boundary term

As in even dimension, we start again by reshaping the first term on the right-hand side in (2.7).

Proposition 4.3. *Let $n \geq 3$ be an odd natural number and $f, g \in C_c^\infty(\Omega)$. Then the identity*

$$\int_0^\infty v(x,t) \partial_\nu u(x,t) dt = \frac{(-1)^{\frac{n-3}{2}}}{n\omega_n \gamma_n} \int_{\mathbb{R}^n} g(y) \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(x, \|x-y\|) dy \quad (4.3)$$

holds for every $x \in \partial\Omega$.

Proof. Inserting solution formula (2.3) for the function v and applying integration by parts $(n - 3)/2$ -times lead to

$$\int_0^\infty v(x, t) \partial_\nu u(x, t) dt = \frac{(-1)^{\frac{n-3}{2}}}{n\omega_n \gamma_n} \int_0^\infty \mathcal{M}g(x, t) \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(x, t) dt$$

Then, by using polar coordinates and the substitution y with $x - y$ we obtain

$$\begin{aligned} \int_0^\infty v(x, t) \partial_\nu u(x, t) dt &= \frac{(-1)^{\frac{n-3}{2}}}{n\omega_n \gamma_n} \int_{\mathbb{R}^n} g(x + y) \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(x, \|y\|) dy \\ &= \frac{(-1)^{\frac{n-3}{2}}}{n\omega_n \gamma_n} \int_{\mathbb{R}^n} g(y) \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(x, \|x - y\|) dy. \end{aligned}$$

□

4.3 Manipulation of the interior term

In view of Lemma 3.6 and 3.7, we analogously transform the second term in the odd case as follows:

Lemma 4.4. *Let $n \geq 3$ be an odd natural number and $f, g \in C_c^\infty(\Omega)$. Then we have*

$$\begin{aligned} &\int_\Omega \int_0^\infty u(x, t) v(x, t) dt dx \\ &= \frac{(-1)^{\frac{n-1}{2}} 2^{n-1}}{\gamma_n^2} \lim_{m, k \rightarrow \infty} \int_{\mathbb{R}^n} \int_0^\infty \int_0^\infty \varphi_m(x) t^{n-1} r^{n-1} \mathcal{M}f(x, t) \mathcal{M}g(x, r) \\ &\quad \cdot \Phi_k^{(n-1)}(t^2 - r^2) dr dt dx \end{aligned}$$

where $(\varphi_m)_{m \in \mathbb{N}}$ is a family of bounded and integrable functions converging pointwise to χ_Ω and $(\Phi_k)_{k \in \mathbb{N}}$ a family of smooth functions converging pointwise to the Heaviside function $H: \mathbb{R} \rightarrow \mathbb{R}$ almost everywhere.

Proof. From solution formula 2.3 we deduce

$$v(x, t) = \int_0^t \partial_r v(x, t) dr = \frac{1}{\gamma_n} \int_0^\infty H(t^2 - r^2) \mathcal{D}_r^{\frac{n-1}{2}} (r^{n-2} \mathcal{M}g(x, r)) r dr.$$

This implies

$$\begin{aligned} &\int_\Omega \int_0^\infty u(x, t) v(x, t) dt dx \\ &= \frac{1}{\gamma_n^2} \int_\Omega \int_0^\infty \int_0^\infty H(t^2 - r^2) \mathcal{D}_t^{\frac{n-1}{2}} (t^{n-2} \mathcal{M}f(x, t)) t \mathcal{D}_r^{\frac{n-1}{2}} (r^{n-2} \mathcal{M}g(x, r)) r dr dt dx \\ &= \frac{(-2)^{\frac{n-1}{2}}}{\gamma_n^2} \int_\Omega \int_0^\infty \int_0^\infty H(t^2 - r^2) t^{n-1} \mathcal{M}f(x, t) \mathcal{D}_r^{\frac{n-1}{2}} (r^{n-2} \mathcal{M}g(x, r)) r dr dt dx \end{aligned}$$

$$= \frac{(-1)^{\frac{n-1}{2}} 2^{n-1}}{\gamma_n^2} \int_{\Omega} \int_0^{\infty} \int_0^{\infty} H(t^2 - r^2) t^{n-1} \mathcal{M}f(x, t) r^{n-1} \mathcal{M}g(x, r) dr dt dx ,$$

where we applied integration by parts $(n - 1)/2$ -times with respect to t and r . From Lebesgue's dominated convergence theorem we finally obtain the above transformation. \square

Proposition 4.5. *The left double integral in Lemma 4.4 can be transformed to*

$$\begin{aligned} \int_{\Omega} \int_0^{\infty} u(x, t) v(x, t) dt dx \\ = \frac{(-1)^{\frac{n-3}{2}}}{2^{n+1} \pi^{n-1}} \int_{\Omega} g(x) \int_{\Omega} f(y) \frac{(\partial_2^{n-2} \mathcal{R} \chi_{\Omega})(\tilde{n}(x, y), \tilde{s}(x, y))}{\|x - y\|^{n-1}} dy dx . \end{aligned}$$

Proof. For the proof, we use again the approximation of identity $(\psi_{\mu, \frac{1}{m}})_{m \in \mathbb{N}}$ from Lemma 2.1 with $\mu = \frac{n}{2} + 1$ and set again $\varphi_m := \chi_{\Omega} * \psi_{\mu, \frac{1}{m}}$ for $m \in \mathbb{N}$.

From Lemma 4.4 we obtain

$$\begin{aligned} \int_{\Omega} \int_0^{\infty} u(x, t) v(x, t) dt dx \\ = \frac{(-1)^{\frac{n-1}{2}} 2^{n-1}}{n^2 \omega_n^2 \gamma_n^2} \lim_{m, k \rightarrow \infty} \int_{\mathbb{R}^n} \int_{\Omega} \int_{\Omega} g(y) f(z) \varphi_m(x) \\ \cdot \Phi_k^{(n-1)}(\|x - y\|^2 - \|x - z\|^2) dz dy dx \end{aligned}$$

by using polar coordinates. Then the same arguments as in the proof Proposition 3.8 give

$$\begin{aligned} \int_{\Omega} \int_0^{\infty} u(x, t) v(x, t) dt dx \\ = \frac{(-1)^{\frac{n-1}{2}}}{n^2 \omega_n^2 \gamma_n^2} \lim_{m \rightarrow \infty} \int_{\Omega} g(y) \int_{\Omega} \frac{f(z)}{\|z - y\|^{n-1}} \\ \cdot \int_{\mathbb{R}} \partial_2^{n-1} \mathcal{R} \varphi_m(\tilde{n}(y, z), s) H(2\|z - y\|(s - \tilde{s}(y, z))) ds dz dy , \end{aligned}$$

where the inner integral can be evaluated to

$$\int_{\tilde{s}(y, z)}^{\infty} \partial_2^{n-1} \mathcal{R} \varphi_m(\tilde{n}(y, z), s) ds = -\partial_2^{n-2} \mathcal{R} \varphi_m(\tilde{n}(y, z), \tilde{s}(y, z)) .$$

Finally, we can use the proof of Proposition 3.8 (iii) to deduce the desired transformation. \square

4.4 Proof of Theorem 4.1

As a first step, we see that the first term in 2.7 equals

$$\begin{aligned} & \int_{\partial\Omega} \int_0^\infty v(x, t) \partial_\nu u(x, t) dt \\ &= \frac{1}{2^{\frac{n+1}{2}} \pi^{\frac{n-1}{2}}} (-1)^{\frac{n-3}{2}} \int_{\Omega} g(x) \int_{\partial\Omega} \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(y, \|x-y\|) d\sigma(y) dx \quad (4.4) \end{aligned}$$

by changing the order of integration. Next, we apply the substitution rule with the diffeomorphism Φ as in the proof of Theorem 3.1 (3.11) and partial integration on the right integral in Proposition 4.5 to obtain

$$\begin{aligned} & \int_{\Omega} \int_0^\infty \Delta(uv)(x, t) dt dx \\ &= \frac{(-1)^{\frac{n-3}{2}}}{2^{n+1} \pi^{n-1}} \int_{\Omega} g(x) \int_{\Omega} f(y) \frac{(\partial_2^n \mathcal{R}_{\chi\Omega})(\tilde{n}(x, y), \tilde{s}(x, y))}{\|x-y\|^{n-1}} dy dx. \end{aligned}$$

Hence we have

$$\begin{aligned} & \int_{\Omega} f(x) g(x) \\ &= \int_{\Omega} g(x) \left(\frac{(-1)^{\frac{n-3}{2}}}{(2\pi)^{\frac{n-1}{2}}} \int_{\partial\Omega} \left(\frac{1}{t} \partial_t\right)^{\frac{n-3}{2}} \left(\frac{1}{t} \partial_\nu u\right)(y, \|x-y\|) d\sigma(y) + \mathcal{K}_{\Omega} f(x) \right) dx \end{aligned}$$

for every test function $g \in C_c^\infty(\Omega)$, which shows the claimed inversion formula in odd dimension.

5 Conclusion

In this article we studied the problem of determining the initial data of the wave equation from Neumann traces in arbitrary dimension. This problem is particularly interesting in PAT, where the aim is to recover the initial pressure distribution $f: \mathbb{R}^n \rightarrow \mathbb{R}$ from measurements on some boundary enclosing the unknown object. We derived explicit inversion formulas for Neumann measurements on smooth boundaries of convex domains up to an additional integral operator depending on the unknown function f . As we have seen, this integral operator vanishes for elliptical domains which results in exact reconstruction.

By taking a closer look to the inversion formulas 3.1 and 4.1, we observe that the formula for odd dimension requires only knowledge of Neumann traces on a finite time interval. This follows simply from the fact that the distance between two points inside a bounded domains is always smaller than its diameter. However in even dimensions, the inversion formula requires knowledge of the Neumann trace for all positive times. In practice, only measurements on a finite time interval are known. Therefore, we intend

to investigate inversion formulas that only require data on a finite time interval in even dimensions as well.

In the case of two spatial dimension, in [8] we derive an exact inversion formulas for any linear combination of the solution of wave equation and its normal derivative on circular domains. To study an analogous problem in higher dimension is an interesting open issue. For that purpose the derivation of so-called range conditions for the wave equation [3, 14, 4] could be helpful. Another open issue is the development of exact inversion formulas for other special domains.

A Remaining proofs

A.1 Proof of Lemma 2.1

As a first step, we have to show

$$\int_{\mathbb{B}^n(0,1)} (1 - \|x\|^2)^\mu dx = \frac{1}{a}.$$

By using polar coordinates and letting $r = \sqrt{u}$ we see that

$$\int_{\mathbb{B}^n(0,1)} (1 - \|x\|^2)^\mu dx = n\omega_n \int_0^1 (1 - r^2)^\mu r^{n-1} dr = \frac{n\omega_n}{2} \int_0^1 (1 - u)^\mu u^{\frac{n-2}{2}} du,$$

where $\omega_n := \text{vol}(\mathbb{B}^n(0,1))$ denotes the volume of the n -dimensional unit ball. Then applying integration by parts μ -times yields

$$\begin{aligned} \int_{\mathbb{B}^n(0,1)} (1 - \|x\|^2)^\mu dx &= \frac{n\omega_n}{2} \frac{\mu!}{\left(\frac{n-2}{2} + 1\right) \cdots \left(\frac{n-2}{2} + \mu + 1\right)} \\ &= \frac{n\omega_n}{2} \frac{\Gamma(\mu + 1)\Gamma(\frac{n}{2})}{\Gamma(\frac{n}{2} + \mu + 1)} = \frac{1}{a}, \end{aligned}$$

where we used the identities $\omega_n = \pi^{n/2}/\Gamma(\frac{n}{2} + 1)$ and $\Gamma(\frac{n}{2} + 1) = \frac{n}{2}\Gamma(\frac{n}{2})$.

To prove the second statement, we first show (2.1). By using polar coordinates and letting $r = \sqrt{u}$ again we have

$$\begin{aligned} \mathcal{R}\psi_{\mu,\varepsilon}(\theta, s) &= \frac{1}{\varepsilon^n a} \int_{\mathbb{B}^{n-1}(0, \sqrt{\varepsilon^2 - s^2})} \left(1 - \frac{\|s\theta + \sum_{i=1}^{n-1} x_i \theta_i\|^2}{\varepsilon^2}\right)^\nu dx \\ &= \frac{1}{\varepsilon^n a} \int_{\mathbb{B}^{n-1}(0, \sqrt{\varepsilon^2 - s^2})} \left(1 - \frac{s^2 + \|x\|^2}{\varepsilon^2}\right)^\nu dx \\ &= \frac{(n-1)\omega_{n-1}}{\varepsilon^n a} \int_0^{\sqrt{\varepsilon^2 - s^2}} \left(1 - \frac{s^2 + r^2}{\varepsilon^2}\right)^\nu r^{n-2} dr \\ &= \frac{(n-1)\omega_{n-1}}{2\varepsilon^n a} \int_0^{\varepsilon^2 - s^2} \left(1 - \frac{s^2 + u}{\varepsilon^2}\right)^\nu u^{\frac{n-3}{2}} du, \end{aligned}$$

where $(\theta_1, \dots, \theta_{n-1})$ is a orthonormal basis of $E(\theta, s)$. As in the first step, applying integration by parts μ -times and using the same identities as before lead to

$$\begin{aligned} \mathcal{R}\psi_{\mu,\varepsilon}(\theta, s) &= \frac{(n-1)\omega_{n-1}}{2\varepsilon^n a} \frac{\Gamma(\mu+1)\Gamma(\frac{n-1}{2})}{\varepsilon^{2\mu}\Gamma(\frac{n-1}{2} + \mu + 1)} (\varepsilon^2 - s^2)^{\frac{n-3}{2} + \mu + 1} \\ &= \frac{\Gamma(\frac{n}{2} + \mu + 1)}{\varepsilon\sqrt{\pi}\Gamma(\frac{n-1}{2} + \mu + 1)} \left(1 - \frac{s^2}{\varepsilon^2}\right)^{\frac{n-3}{2} + \mu + 1}. \end{aligned}$$

Now, it remains to show $\int_{\mathbb{R}} \mathcal{R}\psi_{\mu,\varepsilon}(\theta, s) ds = 1$. By letting $u = s/\varepsilon$, $x = \cos(u)$ and using the well-known relation

$$\int_{-\pi/2}^{\pi/2} \cos(x)^m dx = \frac{\sqrt{\pi}\Gamma(\frac{m+1}{2})}{\Gamma(\frac{m}{2} + 1)}, \quad m \in \mathbb{N},$$

we finally have

$$\begin{aligned} \int_{\mathbb{R}} \mathcal{R}\psi_{\mu,\varepsilon}(\theta, s) ds &= \frac{\Gamma(\frac{n}{2} + \mu + 1)}{\sqrt{\pi}\Gamma(\frac{n-1}{2} + \mu + 1)} \int_{-\varepsilon}^{\varepsilon} \left(1 - \frac{s^2}{\varepsilon^2}\right)^{\frac{n-3}{2} + \mu + 1} \frac{1}{\varepsilon} ds \\ &= \frac{\Gamma(\frac{n}{2} + \mu + 1)}{\sqrt{\pi}\Gamma(\frac{n-1}{2} + \mu + 1)} \int_{-1}^1 \left(1 - u^2\right)^{\frac{n-3}{2} + \mu + 1} du \\ &= \frac{\Gamma(\frac{n}{2} + \mu + 1)}{\sqrt{\pi}\Gamma(\frac{n-1}{2} + \mu + 1)} \int_{-\pi/2}^{\pi/2} \cos(x)^{n+2\mu} dx = 1. \end{aligned}$$

A.2 Proof of Lemma 2.2

First, we show formula (2.5). Let $f_n: \mathbb{R}^n \rightarrow \mathbb{R}^n: (r, \varphi, \theta_1, \theta_2, \dots, \theta_{n-2}) \mapsto (x_1, \dots, x_n)$ be the n -dimensional polar coordinate map, where

$$\begin{aligned} x_1 &= r \cos \varphi \sin \theta_1 \sin \theta_2 \cdots \sin \theta_{n-2}, \\ x_2 &= r \sin \varphi \sin \theta_1 \sin \theta_2 \cdots \sin \theta_{n-2}, \\ x_3 &= r \cos \theta_1 \sin \theta_2 \cdots \sin \theta_{n-2}, \\ &\vdots \\ x_{n-1} &= r \cos \theta_{n-3} \sin \theta_{n-2}, \\ x_n &= r \cos \theta_{n-2}, \end{aligned}$$

and $g_n: (0, 2\pi) \times (0, \pi)^{n-2} \rightarrow \mathbb{R}^n: (\varphi, \theta_1, \theta_2, \dots, \theta_{n-2}) \mapsto f_n(1, \varphi, \theta_1, \theta_2, \dots, \theta_{n-2})$ a parametrization of \mathbb{S}^{n-1} . Then, for a function $h \in C_c^\infty(\Omega)$ and $(x, t) \in \mathbb{R}^n \times (0, \infty)$ we obtain

$$\int_{\mathbb{B}^n(x,t)} \frac{h(y)}{\sqrt{t^2 - \|y - x\|^2}} dy$$

$$\begin{aligned}
 &= \int_{\mathbb{R}^n} \frac{\chi_{\mathbb{B}^n(0,t)}(y)h(x+y)}{\sqrt{t^2 - \|y\|^2}} dy \\
 &= \int_0^\infty \int_{(0,2\pi) \times (0,\pi)^{n-2}} \frac{\chi_{\mathbb{B}^1(0,t)}(r)h(x+f_n(r,\varphi,\theta))}{\sqrt{t^2 - r^2}} |\det \partial f_n(r,\varphi,\theta)| d(\varphi,\theta) dr
 \end{aligned}$$

by substituting y with $y+x$ and using polar coordinates. Since the Gram determinant of the parametrization $x+rg_n$ of $\partial\mathbb{B}^n(x,t)$ at $(\varphi,\theta) \in (0,2\pi) \times (0,\pi)^{n-2}$ equals $|\det \partial f_n(r,\varphi,\theta)|$ for every $r > 0$, we have

$$\begin{aligned}
 \int_{\mathbb{B}^n(x,t)} \frac{h(y)}{\sqrt{t^2 - \|y-x\|^2}} dy &= \int_0^\infty \frac{\chi_{\mathbb{B}^1(0,t)}(r)}{\sqrt{t^2 - r^2}} \int_{\partial\mathbb{B}^n(x,r)} h(y) d\sigma(y) dr \\
 &= \int_0^t \sigma(\partial\mathbb{B}^n(x,r)) \frac{\mathcal{M}h(x,r)}{\sqrt{t^2 - r^2}} dr.
 \end{aligned}$$

Inserting this identity into (2.2) by replacing h with f and g , and using the relations $\text{vol}(\mathbb{B}^n(x,t)) = t^n \omega_n$ and $\sigma(\partial\mathbb{B}^n(x,r)) = r^{n-1} n \omega_n$ lead to Equality (2.5).

Now we show formula (2.6). According to (2.5), we are left to show that

$$\begin{aligned}
 \left(\frac{1}{t}\partial_t\right)^{\frac{n-2}{2}} \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2 - r^2}} \mathcal{M}h(x,r) dr\right) \\
 = \left(\int_0^t \frac{r}{\sqrt{t^2 - r^2}} \left(\frac{1}{r}\partial_r\right)^{\frac{n-2}{2}} (r^{n-2} \mathcal{M}h(x,r)) dr\right) \quad (\text{A.1})
 \end{aligned}$$

for $h \in C_c^\infty(\Omega)$. First, we observe that application of integration by parts yields

$$\left(\frac{1}{t}\partial_t\right) \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2 - r^2}} \mathcal{M}h(x,r) dr\right) = \int_0^t \sqrt{t^2 - r^2} \partial_r (r^{n-2} \mathcal{M}h(x,r)) dr$$

Then, the Leibniz rule for integrals gives us

$$\left(\frac{1}{t}\partial_t\right) \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2 - r^2}} \mathcal{M}h(x,r) dr\right) = \int_0^t \frac{r}{\sqrt{t^2 - r^2}} \left(\frac{1}{r}\partial_r\right) (r^{n-2} \mathcal{M}h(x,r)) dr.$$

Now, suppose that

$$\left(\frac{1}{t}\partial_t\right)^k \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2 - r^2}} \mathcal{M}h(x,r) dr\right) = \int_0^t \frac{r}{\sqrt{t^2 - r^2}} \left(\frac{1}{r}\partial_r\right)^k (r^{n-2} \mathcal{M}h(x,r)) dr$$

holds for any value $k < \frac{n-2}{2}$. Since

$$\lim_{r \searrow 0} \left(\frac{1}{r}\partial_r\right)^k (r^{n-2} \mathcal{M}h(x,r)) = 0,$$

we obtain from our assumption and partial integration

$$\begin{aligned} & \left(\frac{1}{t}\partial_t\right)^{k+1} \left(\int_0^t \frac{r^{n-1}}{\sqrt{t^2-r^2}} \mathcal{M}h(x,r) dr\right) \\ &= \left(\frac{1}{t}\partial_t\right) \left(\int_0^t \frac{r}{\sqrt{t^2-r^2}} \left(\frac{1}{r}\partial_r\right)^k \left(r^{n-2}\mathcal{M}h(x,r)\right) dr\right) \\ &= \left(\frac{1}{t}\partial_t\right) \left(\int_0^t \sqrt{t^2-r^2} \partial_r \left(\frac{1}{r}\partial_r\right)^k \left(r^{n-2}\mathcal{M}h(x,r)\right)\right) \end{aligned}$$

Hence, another application of the Leibniz rule for integrals implies (A.1).

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